Non-zero constraints in quantitative coupled physics imaging

Giovanni S. Alberti

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Quantitative Tomographic Imaging - Radon meets Bell and Maxwell

Hybrid conductivity imaging [Widlak, Scherzer, 2012]

$$\begin{cases} -\operatorname{div}(\boldsymbol{a} \,\nabla u^i) = 0 & \text{ in } \Omega, \\ u^i = \varphi_i & \text{ on } \partial\Omega. \end{cases}$$

 $u^{i}(x)$ or $a(x) \nabla u^{i}(x)$ or $a(x) \left| \nabla u^{i} \right|^{2}(x)$

Quantitative thermoacoustic tomography [Bal et al., 2011, Ammari et al., 2013]

$$\left\{ \begin{array}{ll} \Delta u^i + (\omega^2 + \mathrm{i}\omega\sigma) \, u^i = 0 & \text{ in } \Omega, \\ u^i = \varphi_i & \text{ on } \partial\Omega. \end{array} \right.$$

$$\sigma(x) \left| u^i \right|^2(x) \qquad \stackrel{?}{\longrightarrow} \quad \boldsymbol{\sigma}$$

MREIT [Seo et al., 2012, Bal and Guo, 2013]

$$\begin{array}{ll} \operatorname{curl} E^{i} = \mathrm{i}\omega H^{i} & \text{in } \Omega, \\ \operatorname{curl} H^{i} = -\mathrm{i}(\omega\varepsilon + \mathrm{i}\sigma)E^{i} & \text{in } \Omega, \\ E^{i} \times \nu = \varphi_{i} \times \nu & \text{on } \partial\Omega. \end{array}$$

$$H^i(x) \longrightarrow \varepsilon, \sigma$$

Hybrid conductivity imaging [Widlak, Scherzer, 2012], Quantitative PAT

$$\begin{cases} -\operatorname{div}(\mathbf{a} \nabla u^i) + \mu u^i = 0 & \text{in } \Omega, \\ u^i = \varphi_i & \text{on } \partial \Omega. \end{cases}$$

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Why do non-zero constraints matter?

Consider for simplicity the hybrid conductivity problem

$$\begin{cases} -\operatorname{div}(\mathbf{a} \,\nabla u) = 0 & \text{ in } \Omega, \\ u = \varphi & \text{ on } \partial\Omega. \end{cases}$$

with internal data ∇u and unknown a.

With 1 measurement:

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This equation may be solved in a if a is known on $\partial \Omega$ and if

$$\nabla u(x) \neq 0, \qquad x \in \Omega.$$

▶ With *d* measurements:

$$\nabla(\log a) \cdot (\nabla u^1, \cdots, \nabla u^d) = -(\Delta u^1, \dots, \Delta u^d)$$
$$\implies \nabla(\log a) = -(\Delta u^1, \dots, \Delta u^d)(\nabla u^1, \cdots, \nabla u^d)^{-1}$$

This equation may be solved in a if a is known at $x_0 \in \partial \Omega$ and

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Main question

Is it possible to find suitable illuminations φ_i so that the corresponding solutions u^i satisfy certain non-zero constraints, such as the absence of critical points?

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Outline of the talk

- The conductivity equation
- 2 The Helmholtz equation
- 3 The Maxwell's equations
- G. S. Alberti and Y. Capdeboscq. Lectures on elliptic methods for hybrid inverse problems. Technical Report 2016-46, SAM, ETH Zürich, 2016.
- Guillaume Bal. Hybrid inverse problems and internal functionals. In *Inverse problems and applications: inside out. II*, volume 60 of *Math. Sci. Res. Inst. Publ.*, pages 325–368. Cambridge Univ. Press, Cambridge, 2013.
- Peter Kuchment. Mathematics of hybrid imaging: a brief review. In *The mathematical legacy of Leon Ehrenpreis*, volume 16 of *Springer Proc. Math.*, pages 183–208. Springer, Milan, 2012.

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Theorem (Alessandrini Magnanini 1994, Bauman et al. 2000, Alessandrini Nesi 2015)

Let $\Omega \subseteq \mathbb{R}^2$ be a $C^{1,\alpha}$ bounded convex domain and $a \in C^{0,\alpha}(\overline{\Omega}; \mathbb{R}^{2 \times 2})$ be uniformly elliptic. Let $u^i \in H^1(\Omega)$ be the solutions to

 $-{\rm div}(a\nabla u^i)=0 \qquad \text{in }\Omega, \qquad \qquad u^i=x_i \qquad \text{on }\partial\Omega.$

Then

$$\det \begin{bmatrix} \nabla u^1(x) & \nabla u^2(x) \end{bmatrix} \neq 0, \qquad x \in \Omega.$$



- ▶ Thus, $\alpha \nabla u^1(x_0) + \beta \nabla u^2(x_0) = 0$
- Set $v(x) = \alpha u^1(x) + \beta u^2(x)$:
 - $-\operatorname{div}(a\nabla v) = 0$ in Ω
 - $\blacktriangleright \nabla v(x_0) = 0$

• Thus, v has a saddle point in x_0

- \blacktriangleright Then v has two oscillations on $\partial \Omega$
- But $v(x) = \alpha x_1 + \beta x_2$ on $\partial \Omega$

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- det [∇u¹(x₀) ∇u²(x₀)] = 0
 Thus, α∇u¹(x₀) + β∇u²(x₀) = 0
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In three dimensions, the above result fails. Several counterexamples:

- 1. Laugesen 1996: the harmonic case ($a\equiv 1)$ for a specific diffeomorphism $\varphi=(\varphi^1,\varphi^2)$
- 2. Briane et al 2004: the non-constant case (homogenization) for a specific diffeomorphism $\varphi=(\varphi^1,\varphi^2)$
- 3. Could it be possible to find (φ^1,φ^2) independently of a so that for every $x\in\Omega$

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Capdeboscq 2015: No! (by using 2.)

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Critical points in 3D

What about critical points: can we find φ independently of a so that

$$\nabla u(x) \neq 0, \qquad x \in \Omega?$$

Theorem (GSA, Bal, Di Cristo, ARMA 2017)

Let $\Omega \subseteq \mathbb{R}^3$ be a bounded Lipschitz domain. Take $\varphi \in C(\partial X) \cap H^{\frac{1}{2}}(\partial X)$. There exists a (nonempty open set of) $a \in C^{\infty}(\overline{X})$ such that the solution $u \in H^1(X)$ to

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has a critical point in Ω , namely $\nabla u(x) = 0$ for some $x \in \Omega$.

Can be extended to deal with:

- multiple boundary values;
- multiple critical points (located in arbitrarily small balls);
- and Neumann boundary conditions.

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Alternative approaches

- ► Complex geometrical optics solutions [Sylvester and Uhlmann, 1987]
 - $u^{(t)}(x) = e^{tx_m} \left(\cos(tx_l) + i\sin(tx_l) \right) (1 + \psi_t), \quad t \gg 1.$
 - ▶ If $t \gg 1$ then $u^{(t)}(x) \approx e^{tx_m} (\cos(tx_l) + i\sin(tx_l))$ in C^1 [Bal and Uhlmann, 2010]
 - \blacktriangleright The traces on the boundary of these solutions give the required $\varphi_i \mathbf{s}$
 - Need smooth coefficients, construction depends on coefficients.
 - Only for isotropic coefficients
- Runge approximation [Lax 1956, Bal and Uhlmann 2013]
 - There exist solutions that are locally closed to the solutions of the constant coefficient PDE.
 - Based on unique continuation, non constructive.
 - Also for anisotropic coefficients.
- Stability results without the constraints
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Alternative approaches

- ► Complex geometrical optics solutions [Sylvester and Uhlmann, 1987]
 - $u^{(t)}(x) = e^{tx_m} \left(\cos(tx_l) + i\sin(tx_l) \right) (1 + \psi_t), \quad t \gg 1.$
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Outline of the talk

The conductivity equation

2 The Helmholtz equation

3 The Maxwell's equations

We now consider the Helmholtz equation

$$\left\{ \begin{array}{ll} \Delta u^i_\omega + \left(\omega^2 \varepsilon + \mathrm{i} \omega \sigma \right) u^i_\omega = 0 & \quad \text{in } \Omega, \\ u^i_\omega = \varphi_i & \quad \text{on } \partial \Omega. \end{array} \right.$$

where $\Omega \subseteq \mathbb{R}^d$, d = 2, 3, $\varepsilon, \sigma \in L^{\infty}(\Omega)$, $\sigma, \varepsilon \leq \Lambda$, $\varepsilon > \Lambda^{-1}$.

We are interested in the constraints:

1.
$$|u_{\omega}^{1}|(x) > 0$$
 (nodal set)
2. $|\det [\nabla u_{\omega}^{2} \cdots \nabla u_{\omega}^{d+1}]|(x) > 0$ (Jacobian)
3. $|\det \begin{bmatrix} u_{\omega}^{1} \cdots u_{\omega}^{d+1} \\ \nabla u_{\omega}^{1} \cdots \nabla u_{\omega}^{d+1} \end{bmatrix}|(x) > 0$ ("augmented" Jacobian

- Since solutions uⁱ_w are oscillatory, they will not in general satisfy these contraints. The Radó-Kneser-Choquet theorem (constraint 2.) fails.
- \blacktriangleright CGO solutions and the Runge approximation may be used also in this case, but the corresponding boundary conditions φ_i are not explicitly constructed.

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- Is there an alternative approach?

Multi-Frequency Approach: main result

 $K^{(n)}$: uniform partition of $\mathcal{A} = [K_{min}, K_{max}]$ with n points



Theorem (GSA, IP 2013 & CPDE 2015)

There exist C > 0 and $n \in \mathbb{N}^*$ depending only on Ω , Λ and \mathcal{A} such that the following is true. Take

$$\varphi_1 = 1, \qquad \varphi_2 = x_1, \qquad \dots \qquad \varphi_{d+1} = x_d.$$

There exists an open cover

$$\overline{\Omega} = \bigcup_{\omega \in K^{(n)}} \Omega_{\omega}$$

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As an example, let us consider the 1D case with $\varepsilon = 1$ and $\sigma = 0$. 1. $|u_{\omega}^{1}(x)| \geq C$: the zero set of u_{ω}^{1} moves when ω varies:



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Lemma

The map $\mathbb{C} \setminus \sqrt{\Sigma} \longrightarrow C^1(\overline{\Omega})$, $\omega \mapsto u^i_{\omega}$ is holomorphic.

- The set $Z_x = \{\omega \in \mathcal{A} : u_\omega^1(x) = 0\}$ is finite (consider 1. for simplicity)
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Theorem (GSA and Capdeboscq, CM 2016)

Take $\varphi = 1$. Assume that σ and ε are real analytic. The set

$$\left\{(\omega_1,\ldots,\omega_{d+1})\in\mathcal{A}^{d+1}:\min_{\overline{\Omega}}(\left|u_{\omega_1}^{\varphi}\right|+\cdots+\left|u_{\omega_{d+1}}^{\varphi}\right|)>0\right\}$$

is open and dense in \mathcal{A}^{d+1} . In other words, (almost any) d+1 frequencies are ok.

- Classical elliptic regularity theory implies that u^{φ}_{ω} is real analytic
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- Stratification for analytic varieties: $X = \bigcup_p A_p$, A_p analytic submanifolds
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Some related works

► Ammari et al. (2016) have successfully adapted this method to ${\rm div}((\omega \varepsilon + {\rm i}\sigma)\nabla u^i_\omega) = 0.$

▶ In 2D, everything works with $a \in C^{0,\alpha}(\Omega; \mathbb{R}^{2 \times 2})$ and

$$\operatorname{div}(a \nabla u_{\omega}^{i}) + (\omega^{2}\varepsilon + \mathrm{i}\omega\sigma)u_{\omega}^{i} = 0$$

by using the absence of critical points for the conductivity equation.

▶ In 3D, we already know that in general for $\omega = 0$ we may have critical points. What can we do?

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What if $a \not\approx 1$ in 3D?

The case $\omega = 0$ may not be needed for the theory to work:

Theorem (GSA, ARMA 2016)

Suppose $a, \varepsilon \in C^2(\mathbb{R}^3)$ and $\sigma = 0$. For a generic C^2 bounded domain Ω and a generic $\varphi \in C^1(\overline{\Omega})$ there exists a finite $K \subseteq \mathcal{A}$ such that

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► Model

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 \blacktriangleright Internal data: $\psi_{\omega} = |u_{\omega}|^2 \nabla \varepsilon$

• Linearised problem: $D\psi_{\omega}[\varepsilon](\rho) \mapsto \rho$

In order to have well-posedness of the linearised inverse problem we need $\|D\psi_{\omega}[\varepsilon](\rho)\| \ge C \|\rho\|, \qquad \rho \in H^1(\Omega),$

or equivalently $\ker D\psi_{\omega}[\varepsilon] = \{0\}.$

Theorem (Alberti, Ammari, Ruan, 2014) This holds true with a priori determined frequencies K and stability constant C_K .

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 Internal data: ψ_ω = |u_ω|²∇ε
 Linearised problem: Dψ_ω[ε](ρ) ↦ ρ

In order to have well-posedness of the linearised inverse problem we need $\|D\psi_{\omega}[\varepsilon](\rho)\| \ge C \|\rho\|, \qquad \rho \in H^1(\Omega),$

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Numerical experiments









(b) $K = \{15\}$

Numerical experiments







(c) $K = \{20\}$



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(d) $K = \{10, 15, 20\}$

Outline of the talk

1 The conductivity equation

2 The Helmholtz equation

The Maxwell's equations

MREIT [Seo et al., 2012, Bal and Guo, 2013]

$$\begin{cases} \operatorname{curl} E^i = \mathrm{i}\omega H^i & \text{in } \Omega, \\ \operatorname{curl} H^i = -\mathrm{i}(\omega\varepsilon + \mathrm{i}\sigma)E^i & \text{in } \Omega, \\ E^i \times \nu = \varphi_i \times \nu & \text{on } \partial\Omega. \end{cases}$$

$$H^i(x) \xrightarrow{?} \varepsilon, \sigma$$

$$|\det \begin{bmatrix} E^1(x) & E^2(x) & E^3(x) \end{bmatrix}| > 0.$$

- ▶ CGO solutions may be used [Chen Yang, IP 2013].
- The multi-frequency method discussed above works as well [GSA, JDE 2015].
- ▶ In both cases, the regularity of the solutions is a fundamental ingredient.

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Regularity for Maxwell's equations

Theorem (GSA, 2016)

Assume that

$$\varepsilon, \mu \in C^{0,\alpha}(\overline{\Omega}; \mathbb{C}^{3 \times 3}), \qquad \|(\mu, \varepsilon)\|_{C^{0,\alpha}} \leq \Lambda$$

and that are uniformly elliptic (constant Λ). Take $J_e, J_m \in C^{0,\alpha}(\overline{\Omega}; \mathbb{C}^3)$ and $G \in C^{1,\alpha}(\operatorname{curl}, \Omega)$. Let $(E, H) \in H(\operatorname{curl}, \Omega)^2$ be a weak solution of

$$\begin{aligned} \operatorname{curl} H &= \mathrm{i}\omega\varepsilon E + J_e \quad \text{in } \Omega, \\ \operatorname{curl} E &= -\mathrm{i}\omega\mu H + J_m \quad \text{in } \Omega, \\ E &\times \nu = G \times \nu \quad \text{on } \partial\Omega, \end{aligned}$$

Then $E, H \in C^{0, \alpha}(\overline{\Omega}; \mathbb{C}^3)$ and

 $\|(E,H)\|_{C^{0,\alpha}} \leq C \left(\|(E,H)\|_{L^2(\Omega;\mathbb{C}^3)^2} + \|G\|_{C^{1,\alpha}(\operatorname{curl},\Omega)} + \|(J_e,J_m)\|_{C^{0,\alpha}(\overline{\Omega};\mathbb{C}^3)^2}\right)$

for some constant C depending only on $\Omega,\,\Lambda$ and $\omega.$

Take-home message: regularity for Maxwell is exactly as in the elliptic case!

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Conclusions

The inversion in quantitative hybrid imaging often requires the solutions to the direct problem to satisfy certain non-zero constraints.

- It is in general difficult to enforce these constraints a priori (independently of the unknown coefficients), but certain techniques are available:
 - The Radó-Kneser-Choquet theorem and its generalizations (only in 2D, counterexamples in 3D)
 - CGO solutions
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